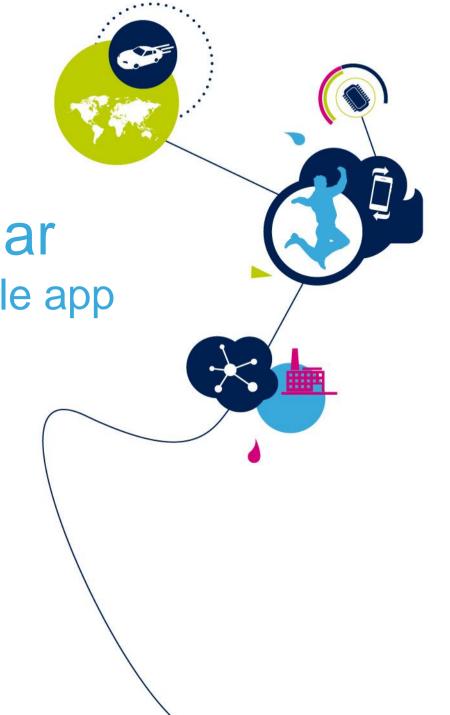
BlueCoin, the Electronic Ear Hands-on LABs using BlueMS mobile app

STMicroelectronics







LAB Preparation

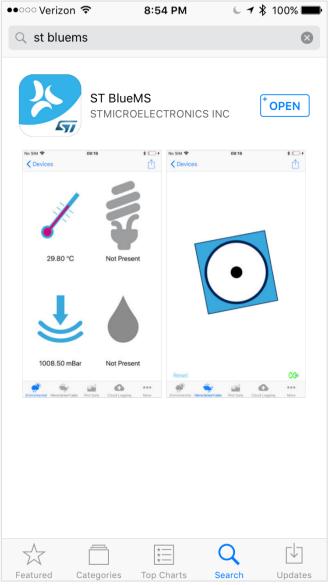


ON YOUR PHONE/TABLET









Agenda 3

www.st.com/bluecoin



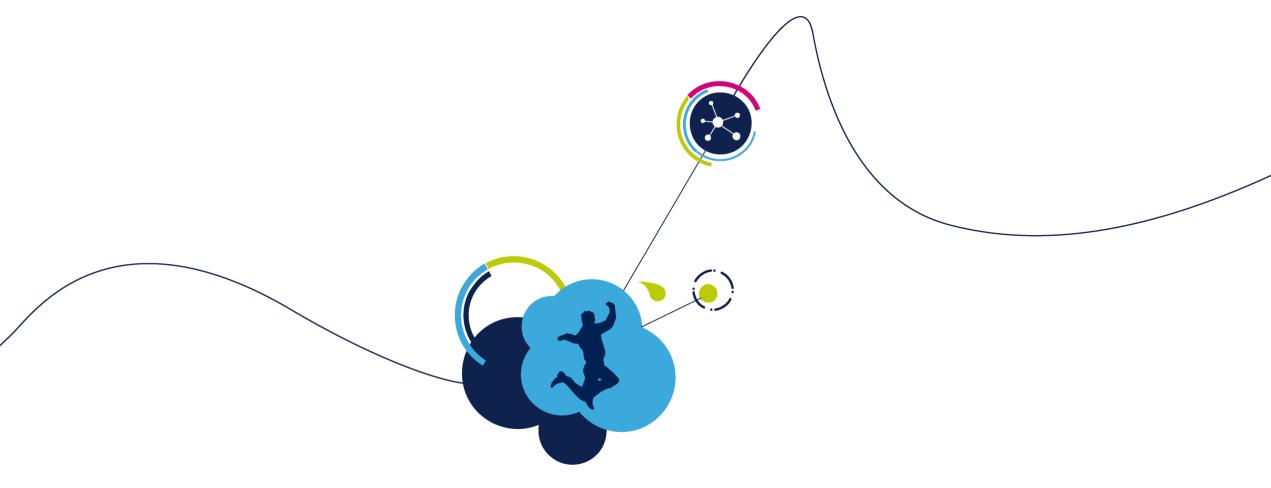
BlueCoin Overview

- How to program the BlueCoin
- Firmware and Software Overview

BlueCoin Hands-on Using the ST BlueMS App

- LAB1: Install the ST BlueMS app
- **DEMO: Firmware Over The Air Update**
- LAB2: Real-Time Data Plot and Log
- LAB3: IBM Watson IoT
- LAB4: Event Detection
- LAB5: Voice over Bluetooth Low Energy
- LAB6: IBM Watson Speech To Text



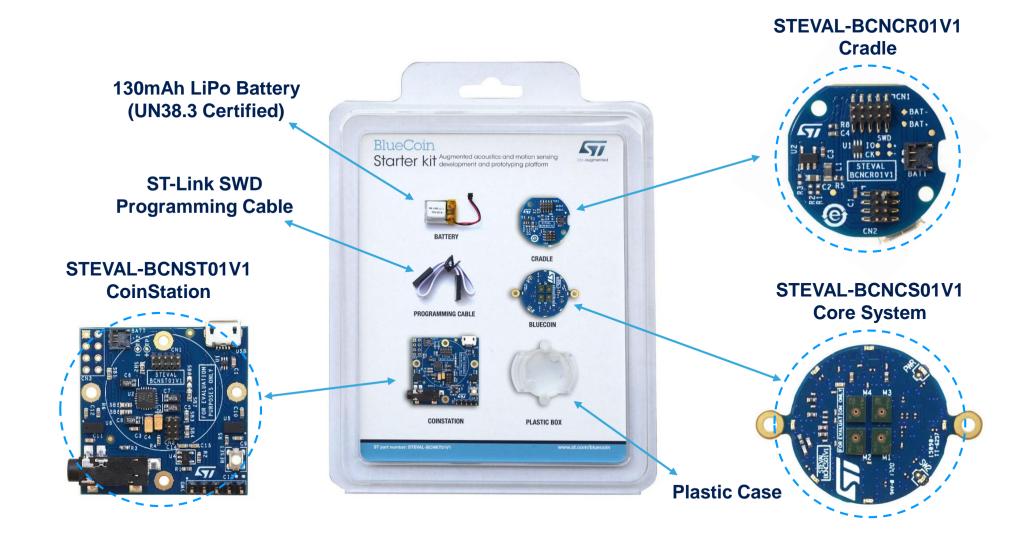


BlueCoin Overview



STEVAL-BCNKT01V1

BlueCoin Starter Kit





BlueCoin - The Robotic Ear 6

Core System: STEVAL-BCNCS01V1

LSM303AGR

3DAcc+3DMag

200μA @ 20 Hz (HR mode) Accel/Mag independent power down mode

LPS22HB

Barometer

1-75Hz. 3-12uA @ 1Hz

4x MP34DT04-C1

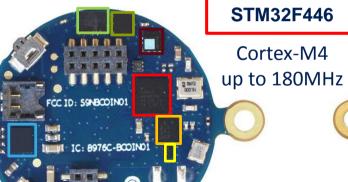
Digital MEMS Microphones 64dB SNR, 120dBSPL

LSM6DSM

3DAcc+3DGyro 0.65mA @ 1.6kHz 9μA @ 12.5Hz

STBC03J

Li-Ion linear battery charger with LDO

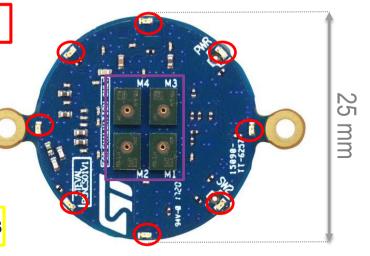


BALF-NRG-01D3

Balun Filter

BlueNRG-MS

Bluetooth low-energy Concurrent master/slave BT4.1

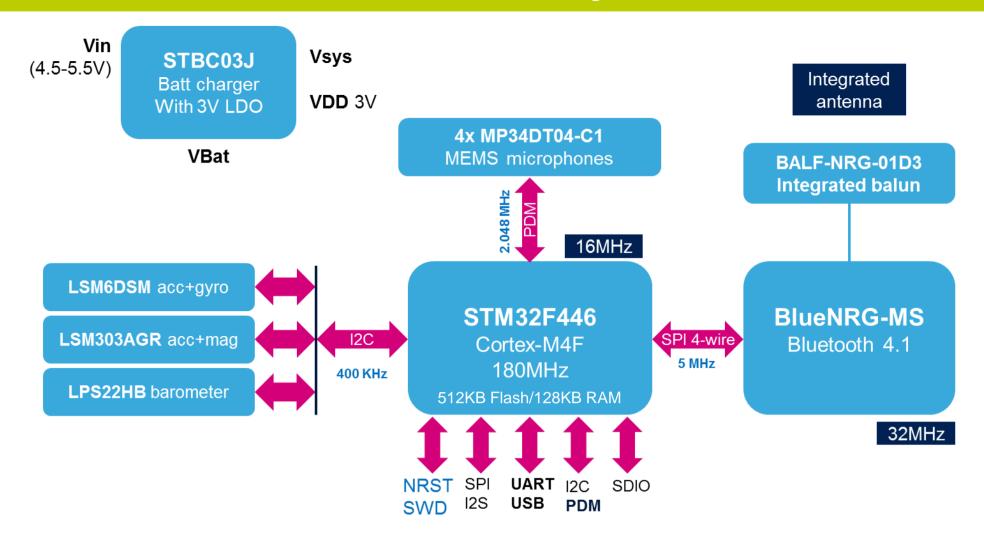






BlueCoin Platform – Hardware overview

BlueCoin Block Diagram



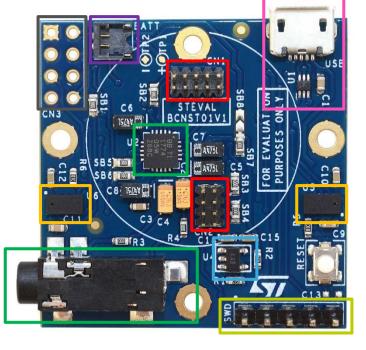


CoinStation: STEVAL-BCNST01V1

Battery Connector

BlueCoin Connectors

Expansion Connector



USBLC6-2P6

ESD protection for USB

2x VL53L0X

Time-of-Flight ranging sensors

LDK120M

2.8V LDO

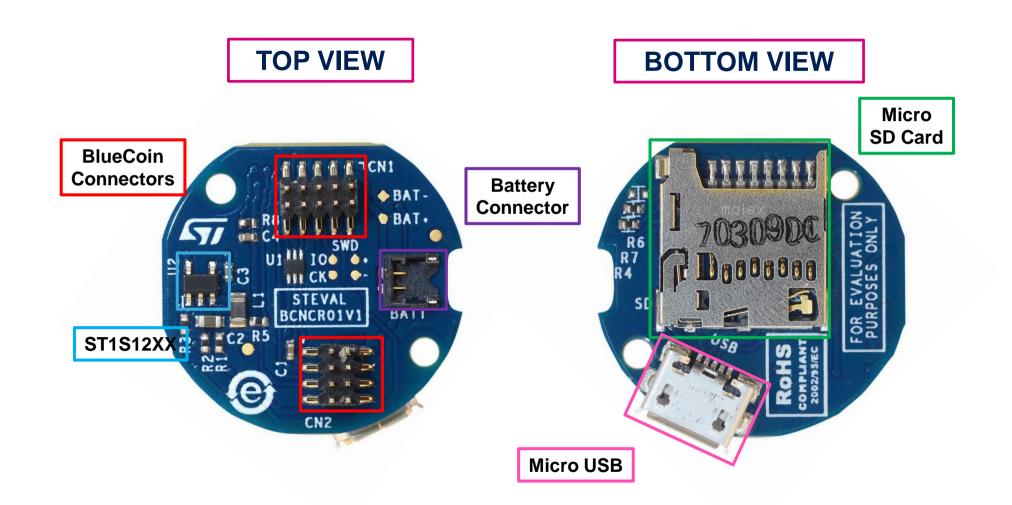
Stereo Audio DAC and 3.5mm Jack





BlueCoin Cradle 9

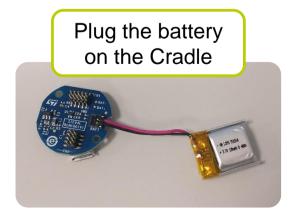
BlueCoin Cradle: STEVAL-BCNCR01V1





How to assemble the portable demo







Fold the Battery below the cradle, insert in the plastic case and secure with the bolts

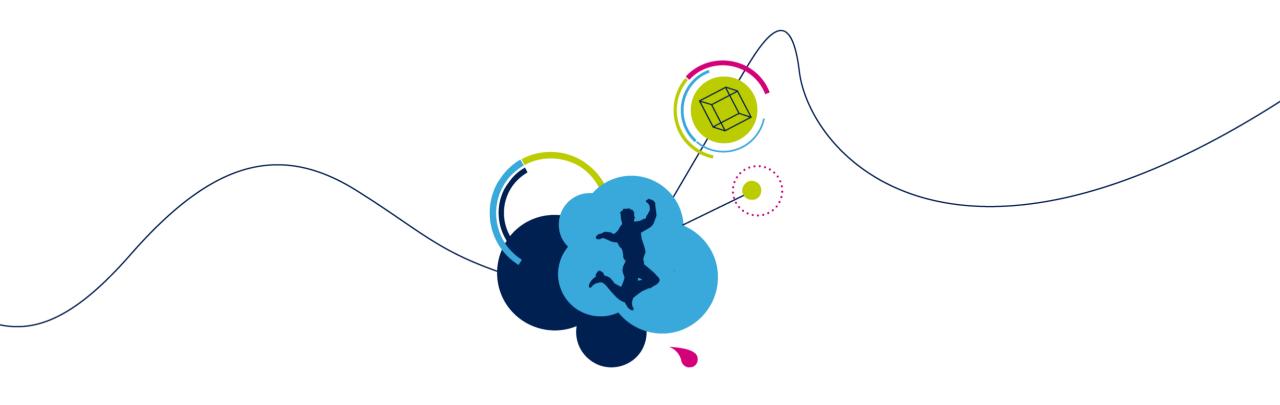






Plug the BlueCoin and secure with the bolts

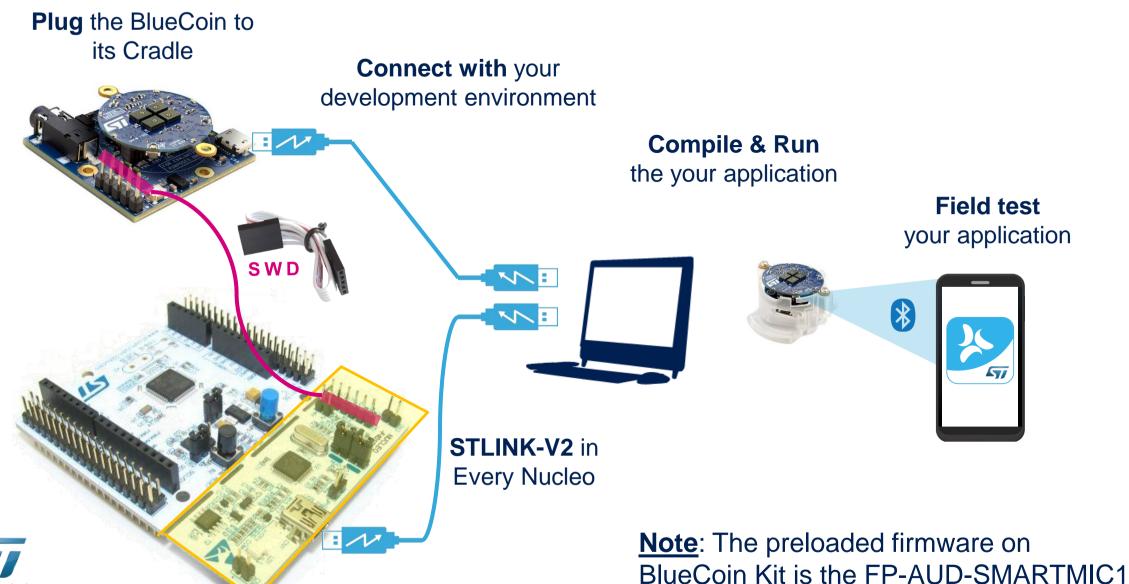




How to program the BlueCoin

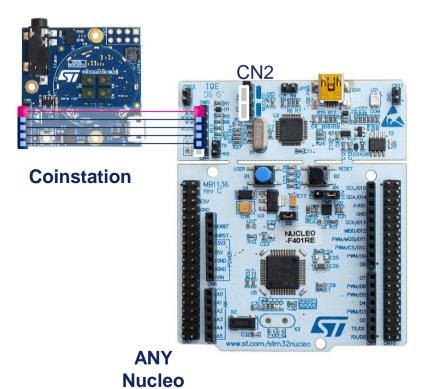


Jump Start Your Project 12



How to Flash the BlueCoin 13

- Remove two jumpers on CN2 of the Nucleo board
- Plug the 5-pin cable to the SWD connectors (pin1 is square, highlight in red below)
- Plug the USB cable of the cradle (if there is a switch: turn it ON) to power the target STM32F446
- Plug the USB cable of the Nucleo board to power the ST-Link/V2
- Drag and drop the * BL.bin on the virtual device (or flash the .bin/.hex using STM32CubeProgrammer)

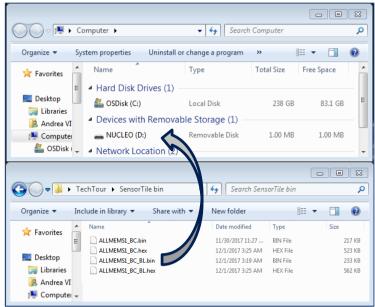




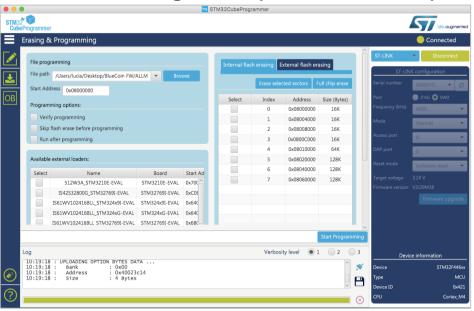
How to Flash the BlueCoin 14

- Remove two jumpers on CN2 of the Nucleo board
- Plug the 5-pin cable to the SWD connectors (pin1 is square, highlight in red below)
- Plug the USB cable of the cradle (if there is a switch: turn it ON) to power the target STM32L4
- Plug the USB cable of the Nucleo board to power the ST-Link/V2
- Drag and drop the * **BL.bin** on the virtual device (or flash the .bin/.hex using STM32CubeProgrammer)

Drag and drop on virtual device (Windows Only)

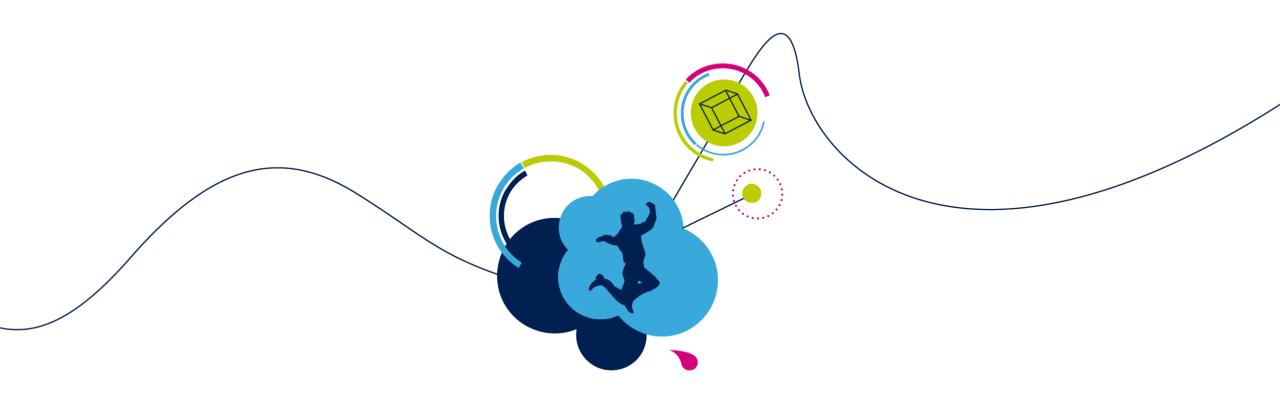


STM32CubeProgrammer (Win, MacOS, Linux)





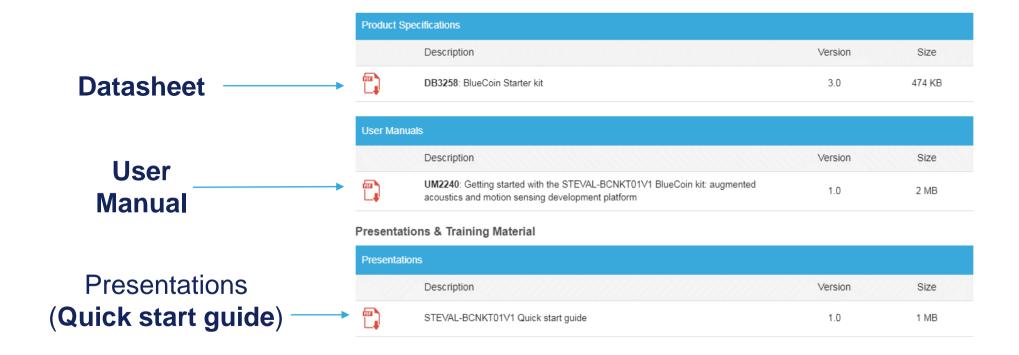
Use ALLMEMS1_BC_BL.bin (from FP-SNS-ALLMEMS1)



Firmware and Software Overview

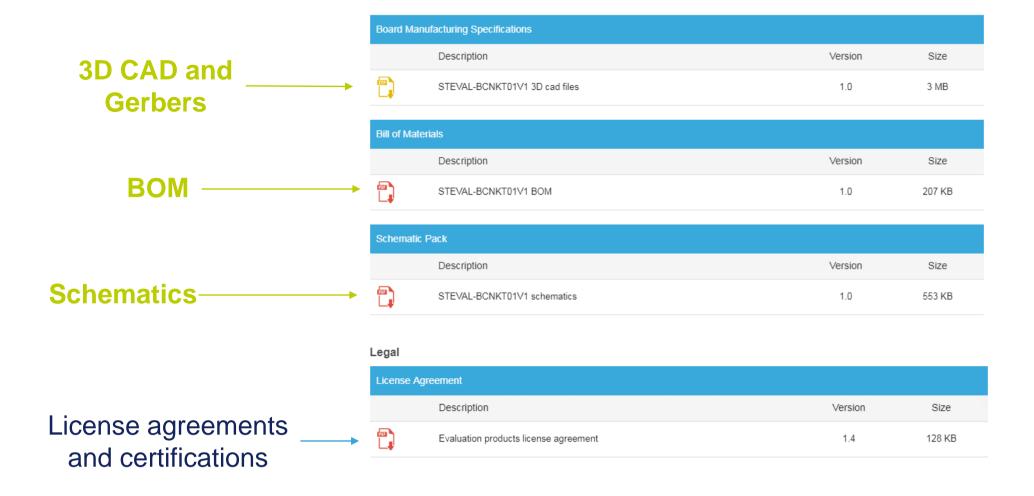


Technical Documentation 16



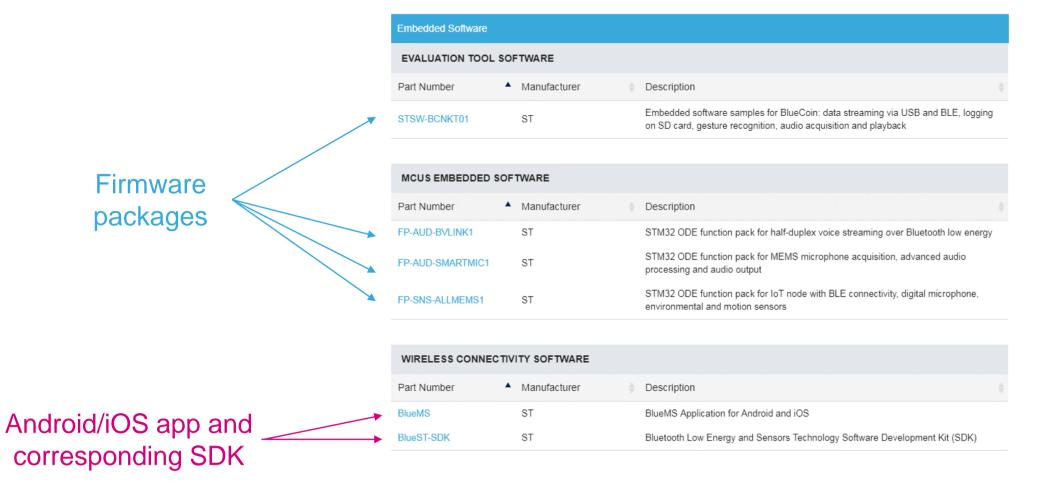


Hardware Resources 17





Tools and Software 18





Hardware, Software, Documentation 19

HARDWARE

STEVAL-BCNKT01V1 BlueCoin kit

FIRMWARE

- **STSW-BCNKT01** FW for beginners (bin + src code)
- **FP-SNS-ALLMEMS1** recommended FW (bin + src code)
 - IoT node with BLE connectivity, digital microphone. environmental and motion sensors
- **FP-AUD BCLINK1** (bin + src code)
 - Half Duplex Voice Streaming over BLE
- FP-AUD SMARTMIC1 (bin + src code)
 - MEMS Microphone acquisition, advanced audio processing and audio output

DOCUMENTATION

- UM2240 getting started with BlueCoin kit
- **UM2249** getting started with STSW-BCNKT01
- **UM2059** getting started with FP-SNS-ALLMEMS1
- **UM2196**: Getting started with the FP-AUD-BVLINK1 STM32 ODE function pack based on half-duplex voice streaming over **BIF**
- **UM2219**: Getting started with STM32 ODE function pack for MEMS microphones acquisition, advanced audio processing and audio output

APPS

- ST BlueMS iOS/Android app (bin)
- **BlueST-SDK** iOS/Android app dev kit (src code)

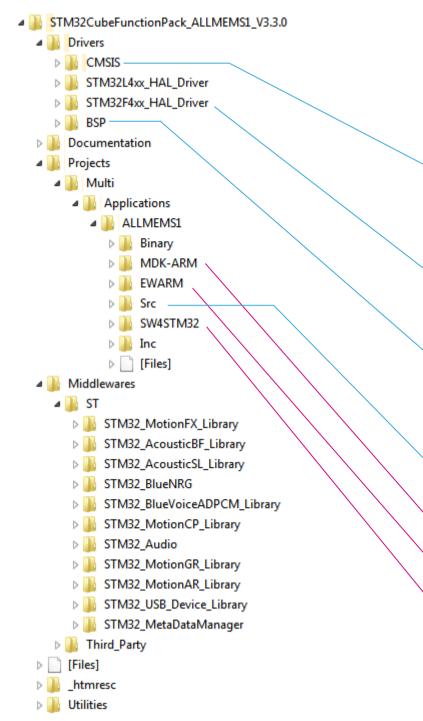
UM1997 getting started with ST BlueMS app





Out-of-Box





FP-SNS-ALLMEMS1

Folder Structure

CMSIS = Cortex Microcontroller Software Interface Standard

DSP library collection (fixed / float)

HAL = Hardware Abstraction Layer

STM32 specific hardware drivers

BSP = Board Support Package

- Components (typ. MEMS sensors)
- Boards (BlueCoin, SensorTile, Nucleo, Nucleo-expansion)

Main.c is in Applications\...\Src\



MDK-ARM **EWARM 806** SW4STM32

Keil project files IAR project files SystemWorkbench



Software Library Licensing 21

 The software libraries are distributed as binaries, with example source code on how to use them.

- A free license agreement is granted.
- The Libraries can run on any STM32 microcontroller, with a generic STM32 MCU locking.



SW Libraries in Function Packages 22

STM320DE software package

Open Development Environment – src code

FP-SNS-ALLMEMS1 BLE + MEMS + digital microphone

Software Libraries

MotionFX, MotionAR, MotionCP, MotionGR, AcousticSL, AcousticBF, BlueVoice

FP-AUD-BVLINK1 BLE + digital microphone BlueVoice

FP-AUD-SMARTMIC1 Digital microphone

AcousticSL, AcousticBF, AcousticEC

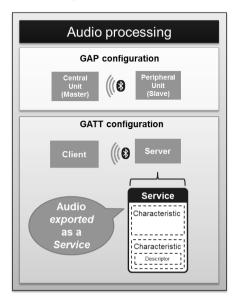


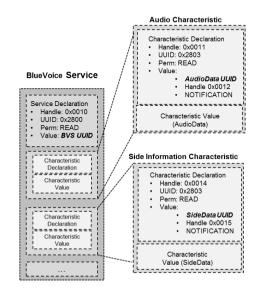
BlueVoice (Voice over BLE)

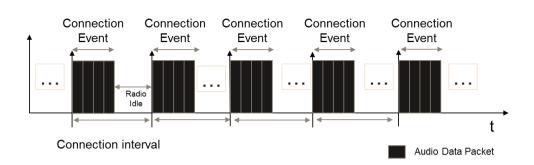
Audio libraries are distributed as <u>binaries</u>, with example source code on how to use them. A <u>free license</u> is granted. They can run on every STM32 microcontroller.

This library is included in the FP-AUD-BVLINK1 and in the FP-SNS-ALLMEMS1 software package.

- BlueVoice (in FP-AUD-BVLINK1) voice streaming over BLE (needs 1 digital microphone, 8kHz PCM, ADPCM compression)
- AcousticBF (in X-CUBE-MEMSMIC1) beam-forming (needs 2 digital mic, cardiod or narrow cardiod, denoise optional filter)
- AcousticSL (in X-CUBE-MEMSMIC1) sound source localization (needs 2/4 mic for 180/360 deg range, three DOA algo)
- AcousticEC (in FP-AUD-SMARTMIC1) echo cancellation (adaptive filter to subtract noise-ref signal, SPEEX MDF algo)









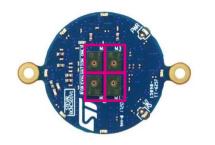
AcousticBF and AcousticSL 24

Audio libraries are distributed as binaries, with example source code on how to use them. A free license is granted. They can run on every STM32 microcontroller.

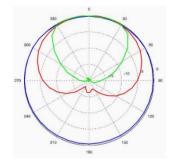
These libraries are included in the **FP-SNS-ALLMEMS1** software package.

- BlueVoice (in FP-AUD-BVLINK1) voice streaming over BLE (needs 1 digital microphone, 8kHz PCM, ADPCM compression)
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- **AcousticEC** (in FP-AUD-SMARTMIC1) echo cancellation (adaptive filter to subtract noise-ref signal, SPEEX MDF algo)

BEAMFORMING







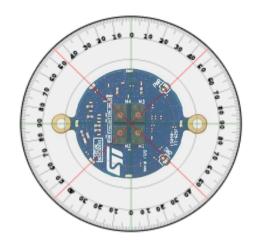
Beam pattern

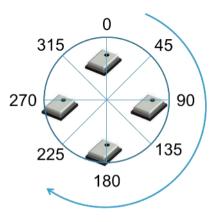
Blue: omnidirectional microphone

Red: «Basic cardioid» mode

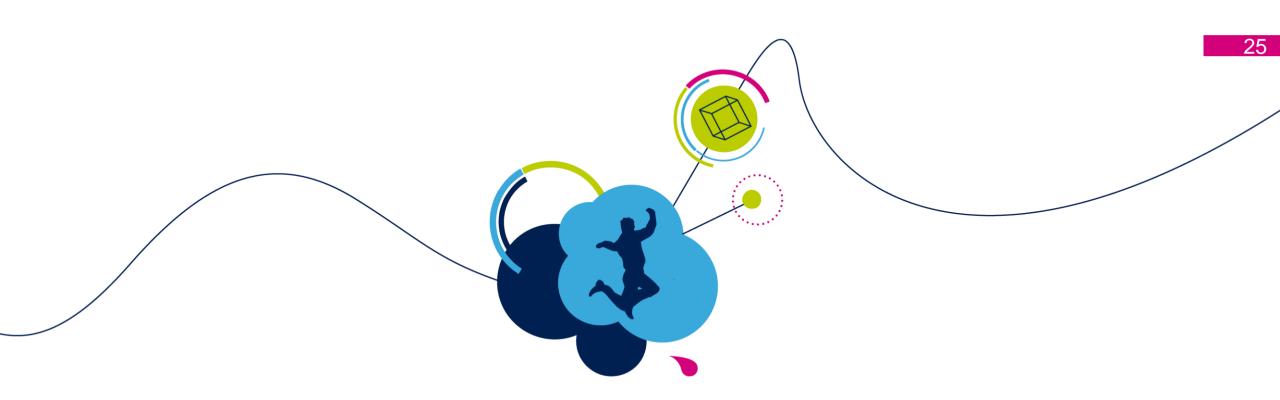
Green: «Strong» mode

SOURCE LOCALIZATION





2 mic 180dea, 4 mic 360 dea



BlueCoin Hands-on Using the ST BlueMS App



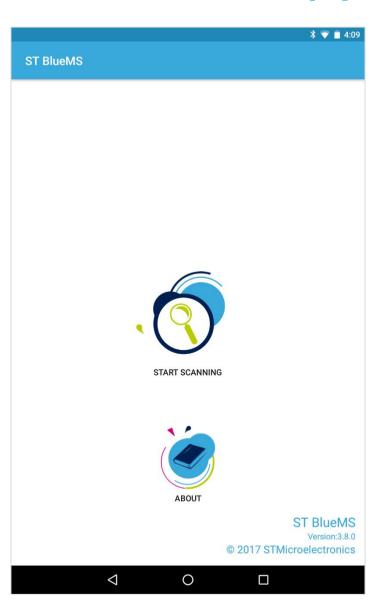






Launch the ST BlueMS app (V3.8.0 or newer) previously installed





Touch "Start discovering"



The name is "CoinXXX"

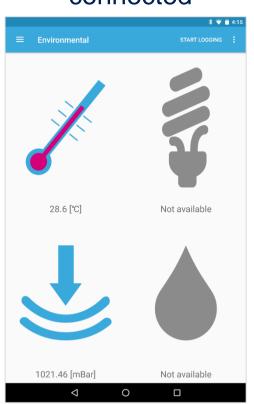
(look at the label on the box)



Select your BlueCoin



You are connected



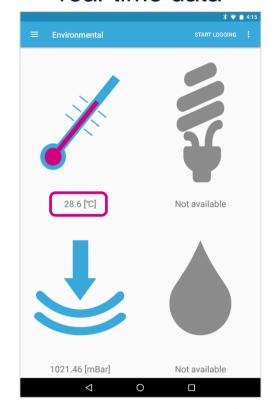
Press PWR for 1s

And wait for the 8 LED to start blinking



NOTE: 2nd line is the MAC address of the specific sample

View the BlueCoin Environmental sensor real-time data







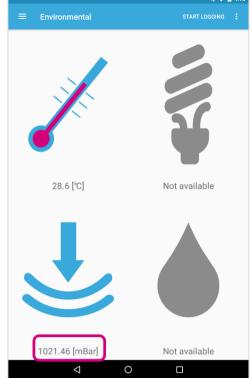
Try to blow some hot air on the BlueCoin to see temperature changes



- Temperature measured using:
 - Internal Temperature sensor of pressure sensor (±1.5C deg accuracy)



View the BlueCoin Environmental sensor real-time data



1021.46



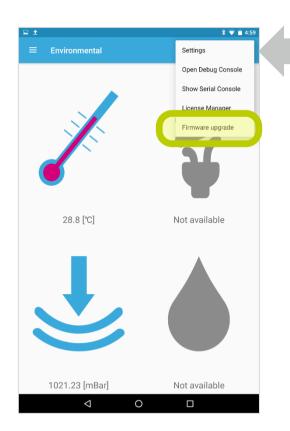
LAB: pressure sensor

Try to move the BlueCoin up/down by 20-30cm (7-12in),

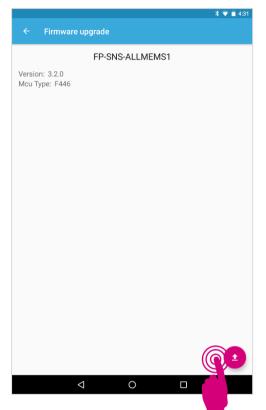
wait a few seconds and observe the change in the barometer reading (mbar).



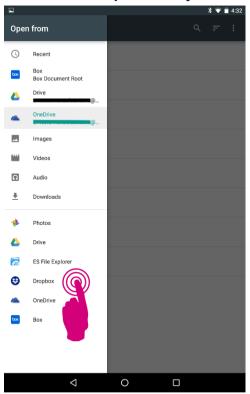




Select "Download & Flash"



Enable and Select the repository





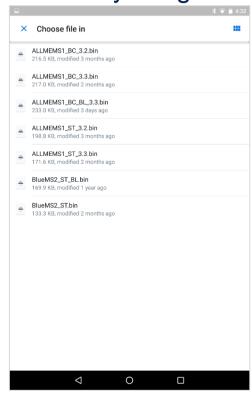
BlueCoin will confirm the integrity of the selected firmware binary before overwriting the current Flash memory image.

Bootloader at 0x 0800 0000

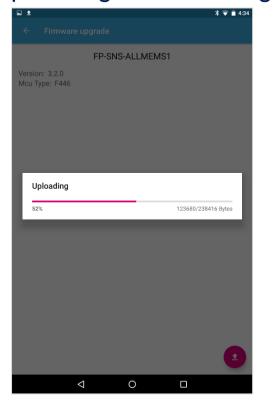
Current application at 0x 0800 **4**000

New application at 0x 0804 0000

Select the firmware binary image



Uploading and Flashing





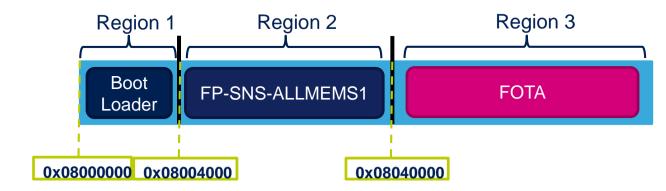


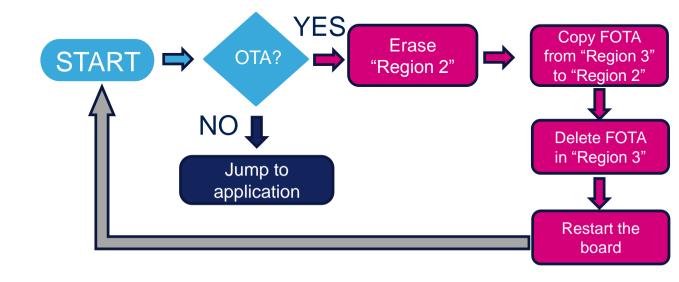
MEMORY ORGANIZATION

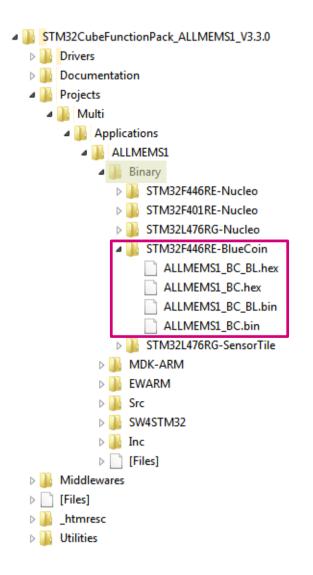
- By default, all BlueCoin FW applications use a bootloader that resides in the first part of the flash memory of the STM32.
- For this reason the memory is organized into 3 different regions

 The bootloader manages the installation of On-The-Air upgrades, if any.

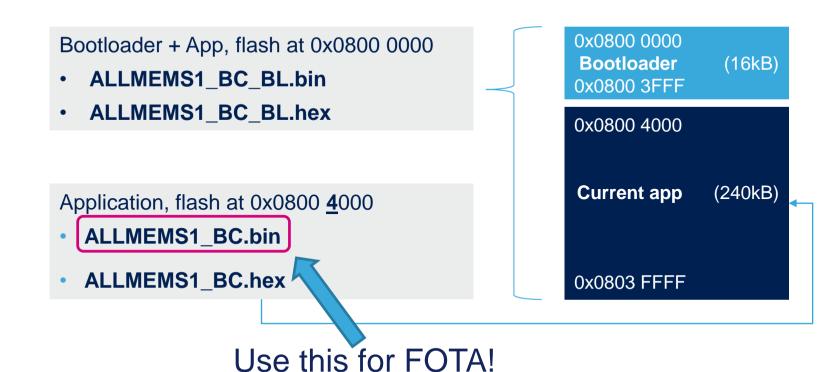








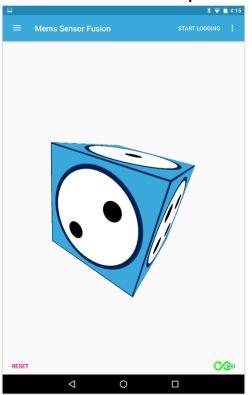
FP-SNS-ALLMEMS1 software package: Binary folder contains two binaries



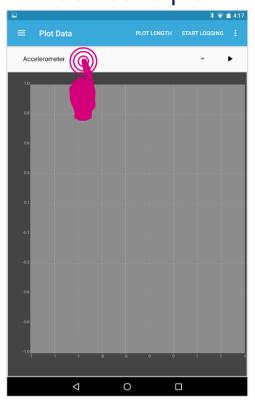


LAB2: Real-time Data Plot 34

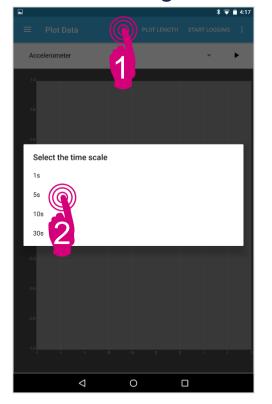
Swipe left to view the real-time data plot



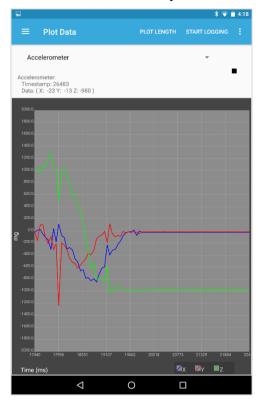
Select the sensor device to plot



Select the Plot lenght



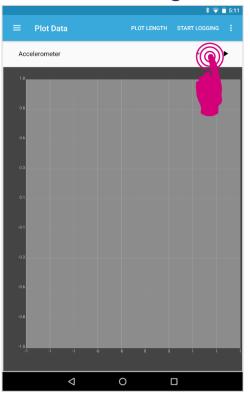
View the realtime data plot





LAB2: Real-time Data Log 35

Start Streaming



Start logging

✓x ✓y ■z

Accelerometer

Data: (X: 269 Y: 926 Z: -79)

Accelerometer:

Time (ms)

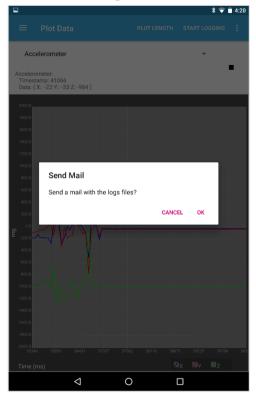
 ∇

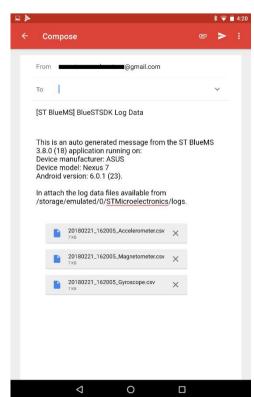
0





Send log data using email







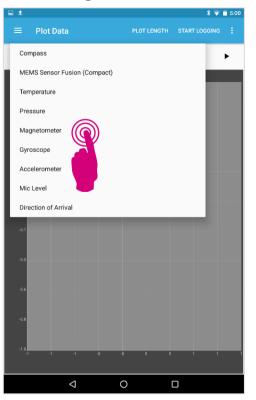
LAB2: Real-time Data Plot

Effects of Magnetic Interference

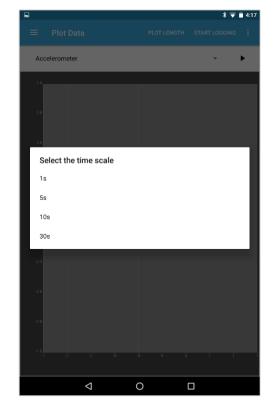
Swipe left to view the real-time data plot



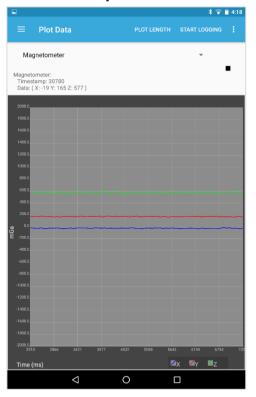
Select the magnetometer



Select the time frame



Magnetic field plot

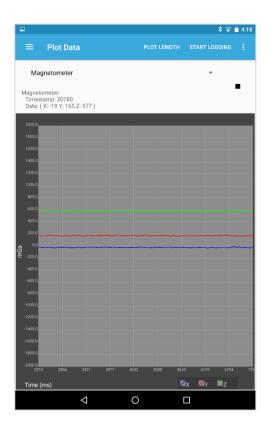






LAB2: Real-time Data Plot

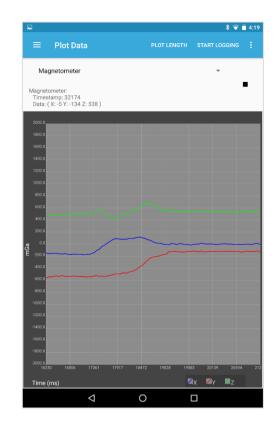
Effects of Magnetic Interference



LAB

Move the smartphone over the BlueCoin





The magnetic field measured by the sensor has changed because of the magnetic field induced by the smartphone (speakers, antennas, battery, currents)



LAB3: IBM Watson IoT Quickstart

Post BlueCoin Sensor Data on IBM Watson

Select "IBMQuickstart"

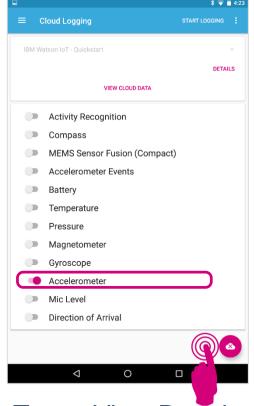


Click "Connect"



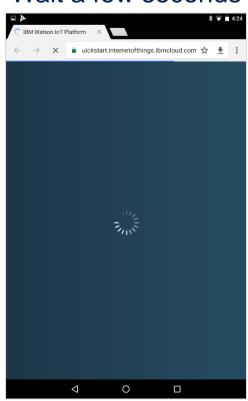
NOTE: MAC address is used is Device Id (see slide 29)

Select a feature



Tap to View Data in the Cloud"

Wait a few seconds

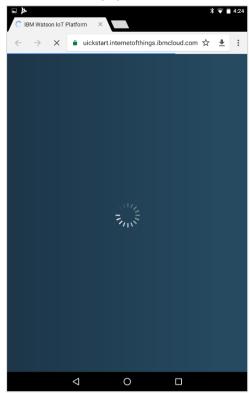




LAB3: IBM Watson IoT Quickstart

Post BlueCoin Sensor Data on IBM Watson

Quickstart will appear



You will see the Plot of selected feature

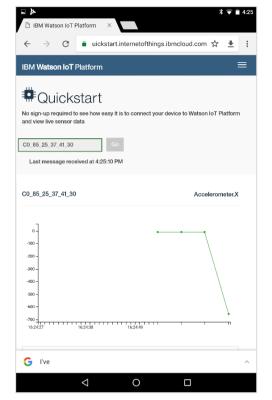
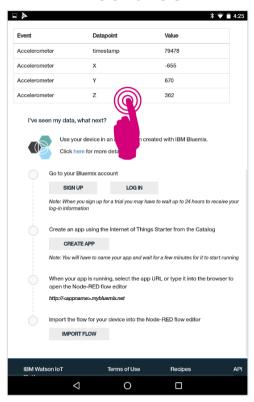
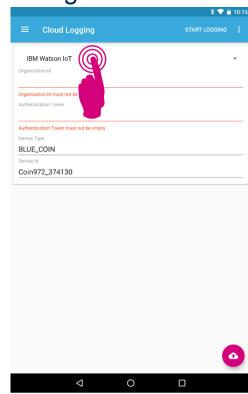


Table of available features



Scroll down to change sensor data or axes

IBM Watson IoT Registered Mode



Organization ID and Authentication Token needed





LSM6DSM

iNEMO inertial module:

always-on 3D accelerometer and 3D gyroscope

Datasheet - production data



- Smart embedded functions: pedometer, step detector and step counter, significant motion and tilt
- Standard interrupts: free-fall, wakeup, 6D/4D orientation, click and double-click

d gyroscope ormal mode te mode tures set

oscope and

sensor

- ±125/±245/±500/±1000/±2000 dps full scale
- Analog supply voltage: 1.71 V to 3.6 V
- SPI & I²C serial interface with main processor data synchronization
- Dedicated gyroscope low-pass filters for UI and OIS applications
- Smart embedded functions: pedometer, step detector and step counter, significant motion and tilt
- Standard interrupts: free-fall, wakeup, 6D/4D orientation, click and double-click

Description

The LSM6DSM is a system-in-package featuring a 3D digital accelerometer and a 3D digital gyroscope performing at 0.65 mA in high-performance mode and enabling always-on low-power features for an optimal motion experience for the consumer.

The LSM6DSM supports main OS requirements, offering real, virtual and batch sensors with 4 kbyte for dynamic data batching.

ST's family of MEMS sensor modules leverages the robust and mature manufacturing processes already used for the production of micromachined accelerometers and gyroscopes.

The various sensing elements are manufactured using specialized micromachining processes, while the IC interfaces are developed using CMOS technology that allows the design of a dedicated circuit which is trimmed to better match the characteristics of the sensing element.

The LSM6DSM has a full-scale acceleration range of $\pm 2/\pm 4/\pm 8/\pm 16$ g and an angular rate range of $\pm 125/\pm 245/\pm 500/\pm 1000/\pm 2000$ dps.

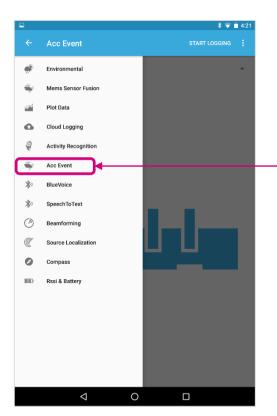
The LSM6DSM fully supports EIS and OIS applications as the module includes a dedicated configurable signal processing path for OIS and auxiliary SPI configurable for both the gyroscope and accelerometer.

High robustness to mechanical shock makes the LSM6DSM the preferred choice of system designers for the creation and manufacturing of reliable products.

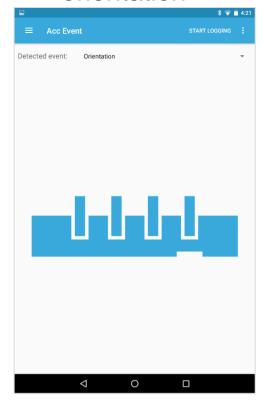
The LOMCDOM is available in a plactic land grid array



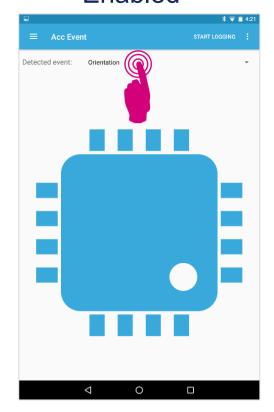
Select "more" Select "Acc Event"



Change orientation



Touch "Event Enabled"



Select another event





The MEMS sensor hardware performs event detection recognition using a programmable interrupt logic block

Select another event







Orientation









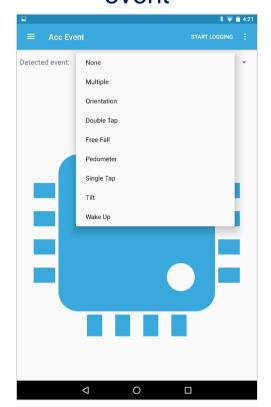




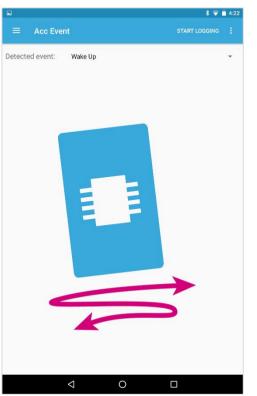


The MEMS sensor hardware performs event detection recognition using a programmable interrupt logic block

Select another event



Wake Up



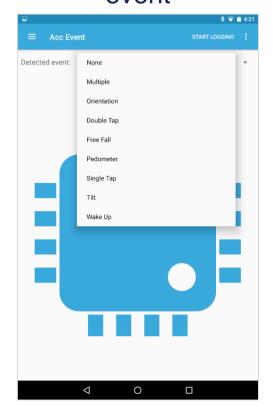
LAB

Shake the device, the acceleration will trigger an interrupt to wake up the MCU (in the meanwhile captured data can be saved to internal FIFO)

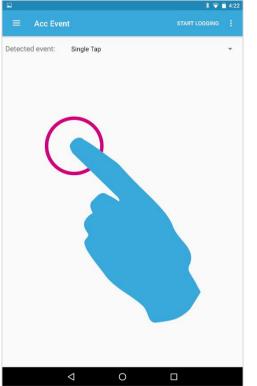


The MEMS sensor hardware performs event detection recognition using a programmable interrupt logic block

Select another event



Single Tap



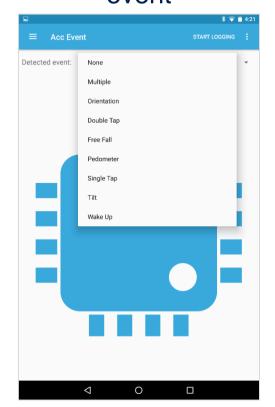
LAB

Tap the device. What happens for the double tap?

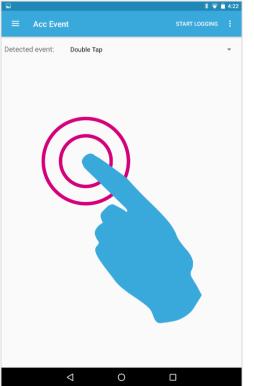


The MEMS sensor hardware performs event detection recognition using a programmable interrupt logic block

Select another event



Double Tap



LAB

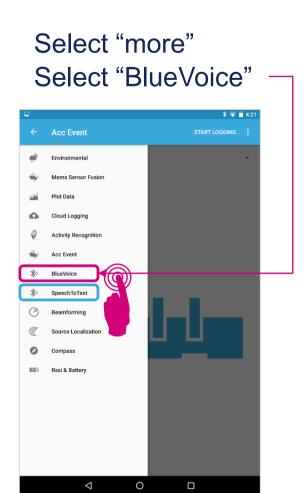
Double tap the device. What happens now for the single tap?



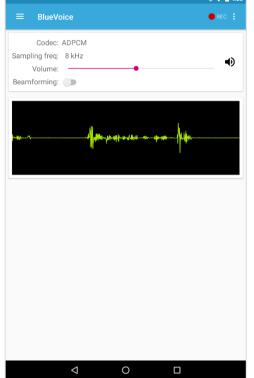
BlueVoice

(voice over Bluetooth LE)

LAB5: Voice over Bluetooth LE 46



Speak to device, hear on phone



Do not silence your phone, must not be vibration only! LAB

Speak into the BlueCoin mic and listen to your phone

(if the mic captures the audio from the phone speaker, a very high pitch sound can happen!)

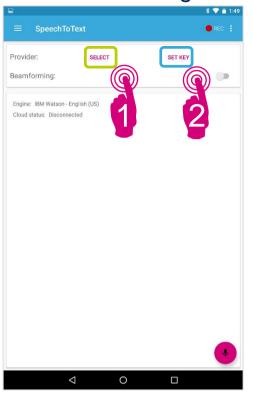


BlueVoice

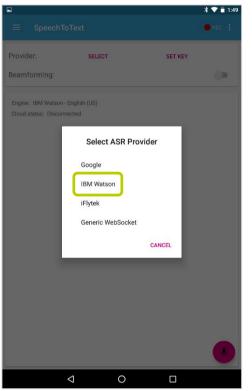
(voice over Bluetooth LE)

LAB6: SpeechToText 47

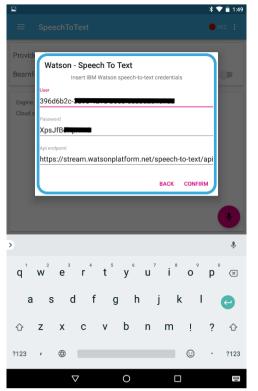
Select ASR Engine

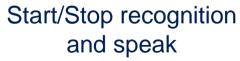


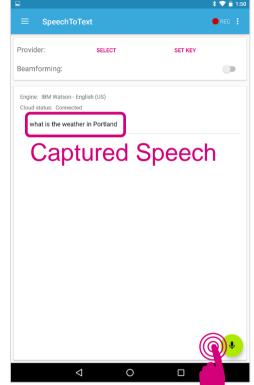
IBM Watson



Add credentials







- **Double Tap** on BlueCoin
- Or Tap on Screen

Alternatively Use WebSocket

