

# STM32 Motor Control

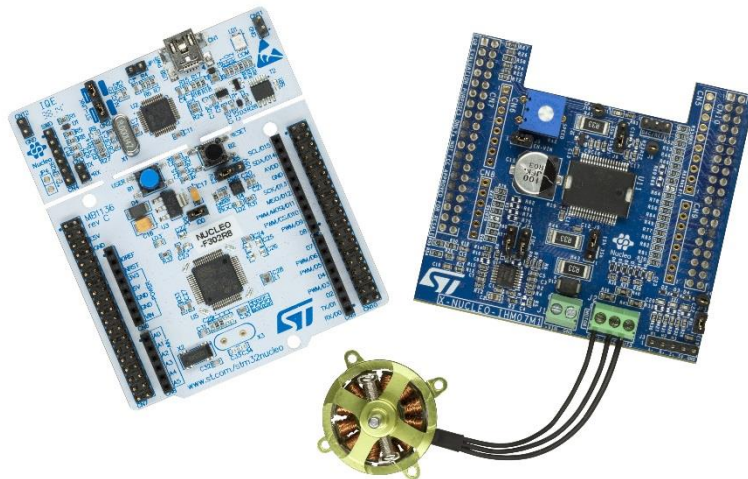
Full motor control ecosystem and SDK version 5.0



Full ecosystem for advanced FOC development of single and dual motor control applications

New SDK v5.0 provides improvements including support of STM32Cube

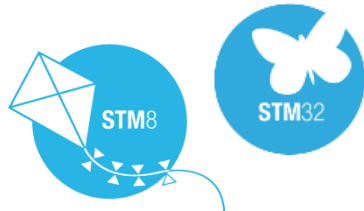
Easy to explore with hardware kits such as the P-NUCLEO-IHM001



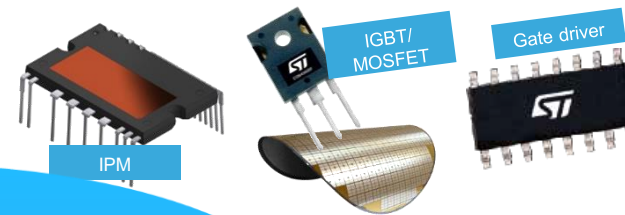
# Motor Control Ecosystem

Complete motor control ecosystem

**MCUs for  
Motor Control (8-32 bit)**



**Inverters  
IPM / discretes**



**ST MC Workbench**



**PC SW GUI**  
Full customization  
and real time  
communication

**Motor Control  
Ecosystem**

**Hardware Boards**



**MC Connector**



**FW library**

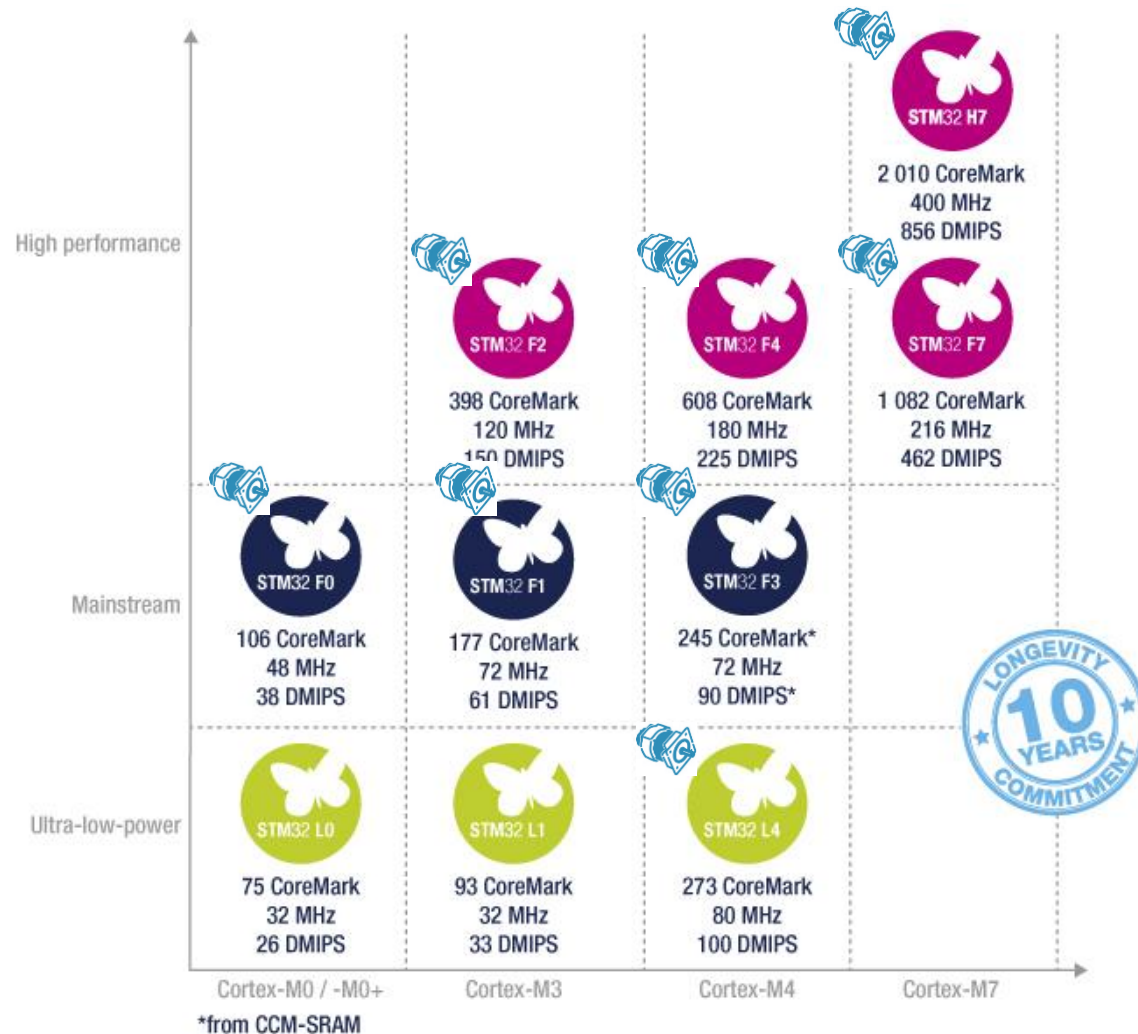
wide range of features &  
algorithms (FOC – 6step)



**Software  
Development  
Kit (SDK)**

# STM32 Portfolio

10 product series / More than 40 product lines



Includes  
advanced motor  
control timer

# STM32 Motor Control Kit

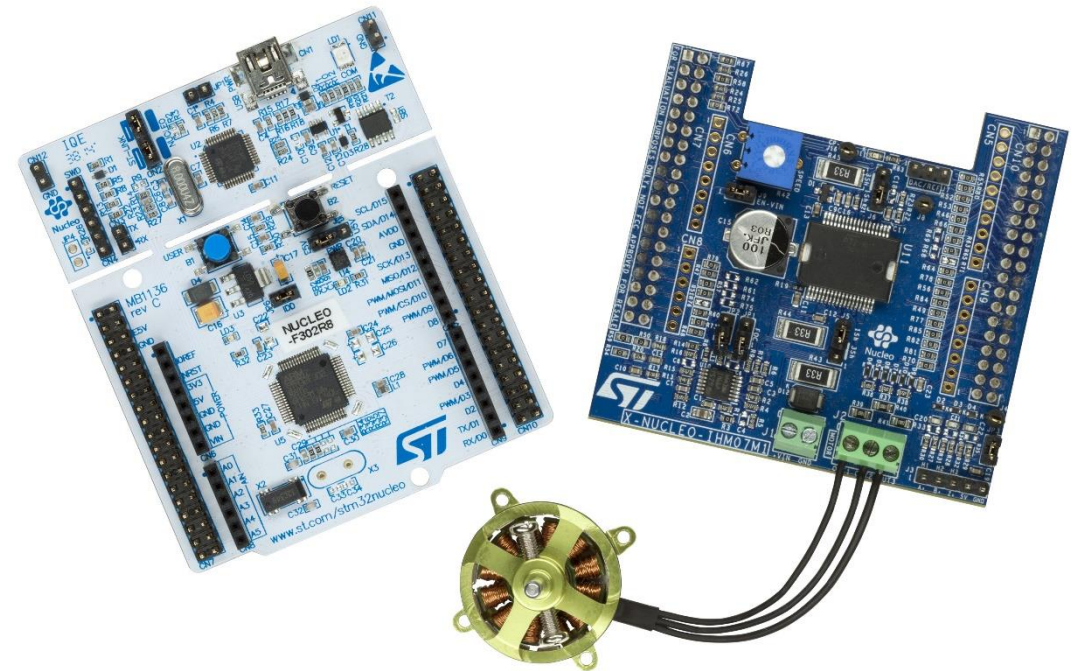
## P-NUCLEO-IHM001 Nucleo Pack

### NUCLEO-F302R8 MCU Control Board

- STM32F302R8T6
- 72MHz Cortex-M4
- 64KB Flash, LQFP64

### X-NUCLEO-IHM07M1 Power Board

- L6230
- Voltage range: 8-48VDC
- Peak Current: 2.8A
- 3 shunt and 1 shunt configurable



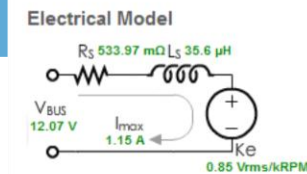
# Motor Control Workflow

## Motor Profiler and Workbench GUI

Set up the  
Hardware



Use motor specs or  
identify the motor  
using  
Motor Profiler



Send commands  
with serial  
communication



Finalize the project  
with Workbench



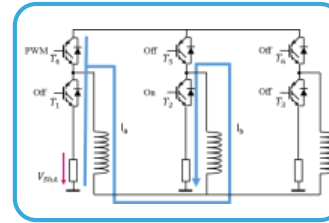


# Motor Profiler

Measures motor parameters typically in less than 1 minute

## Motor stopped

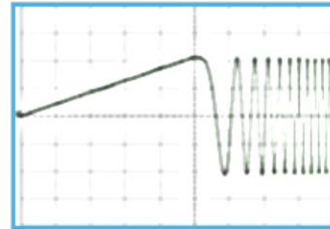
- $R_s$  measurement
- $L_s$  measurement
- Current regulators set-up



10 sec

## Open loop

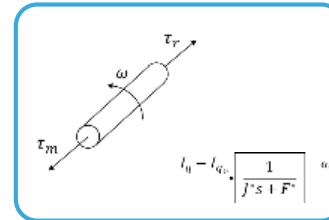
- $K_e$  measurement
- Sensorless state observer set-up
- Switch over



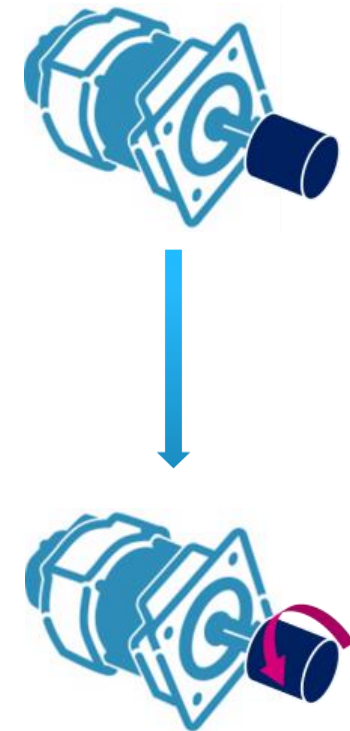
5 sec

## Closed loop

- Friction coefficient measurement
- Moment of inertia measurement
- Speed regulator set-up

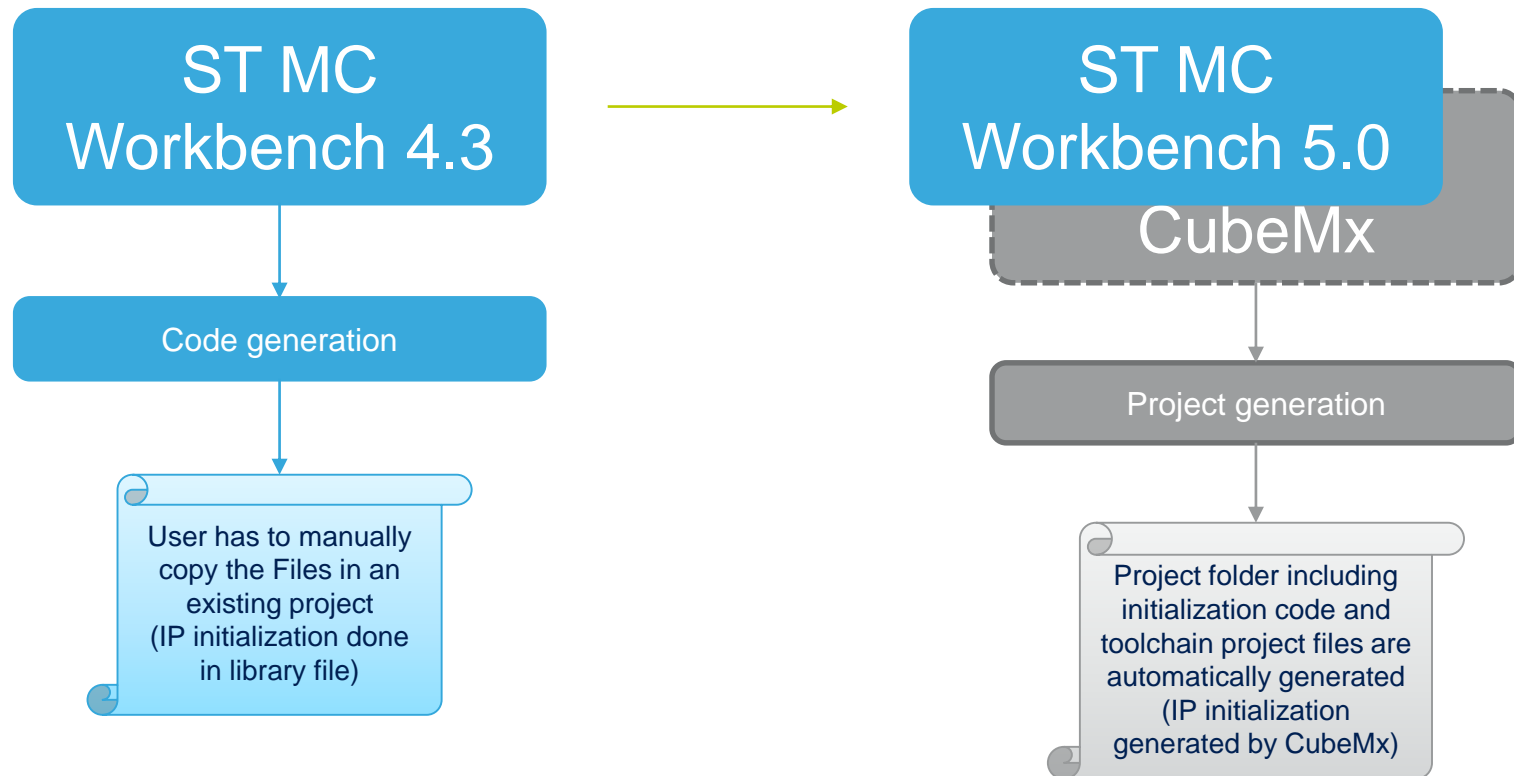


45 sec



# Workbench Now Supports STM32CubeMX

Update from Workbench v4.3 to v5.0



# Workbench Now Supports STM32Cube HAL/LL

Update from Workbench v4.3 to v5.0

The firmware is  
divided into 3 parts:

- User Interface Library
- Motor Cockpit
- Motor Control Library

